GENERAL

autonomous mobile robots sensing control decision making and applications automation and control engineering

Published: September 19, 2026 | Index ID: #-

Autonomous Mobile Robots: Sensing, Control, Decision Making, and Applications in Automation and Control Engineering

In the past decade, autonomous mobile robots (AMRs) have moved from niche research prototypes to mainstream solutions that drive productivity across a wide spectrum of industries. By seamlessly integrating advanced sensing, robust control strategies, intelligent decision making, and sophisticated automation workflows, AMRs are reshaping how factories, warehouses, hospitals, and even farms operate. This article delves into the core technologies that enable these machines, explores their real world applications, and highlights the challenges and future directions that will define the next era of automation and control engineering.

Sensing Technologies in Autonomous Mobile Robots

At the heart of any autonomous system lies its perception capability. Sensors transform raw environmental data into actionable information, allowing a robot to understand its surroundings, detect obstacles, and navigate safely. Modern AMRs rely on a heterogeneous mix of sensors, each bringing unique strengths and trade offs.

Laser Scanners and LIDAR

Light Detection and Ranging (LIDAR) devices emit laser pulses and measure the time it takes for the light to return after reflecting off objects. The result is a high resolution, three dimensional map of the environment, enabling precise localization and obstacle detection even in complex, cluttered spaces. Because LIDAR provides accurate distance measurements regardless of lighting conditions, it is often the backbone of AMR navigation systems.

Camera Systems and Computer Vision

RGB and depth cameras capture visual information that can be processed with computer vision algorithms. Techniques such as feature matching, semantic segmentation, and object recognition allow AMRs to identify specific items, follow visual markers, or adapt to dynamic changes in the workspace. When combined with LIDAR, cameras help resolve ambiguities and enhance the robot’s situational awareness.

IMU, GPS, and Ultrasonic Sensors

Inertial Measurement Units (IMUs) track motion by measuring acceleration and angular velocity, providing critical data for short term pose estimation. Global Positioning System (GPS) modules offer global localization for outdoor deployments, while ultrasonic sensors deliver low cost, short range obstacle detection suitable for indoor environments. Together, these sensors form a complementary suite that ensures reliability across diverse operating conditions.

Sensor Fusion and Data Processing

Raw sensor streams are noisy and often inconsistent. Sensor fusion algorithms—such as the Extended Kalman Filter (EKF) or particle filters—merge data from multiple sources to produce a coherent, high confidence estimate of

the robot’s pose and surroundings. Real time data processing pipelines, accelerated by GPUs or dedicated AI chips, allow AMRs to react within milliseconds, a necessity for safe navigation in dynamic settings.

Control Strategies for Autonomous Mobile Robots

Once the robot perceives its environment, it must decide how to act. Control strategies span from low level motor commands to high level mission planning, each layer building upon the previous to achieve smooth, reliable operation.

Low Level Motor Control

At the foundation, closed loop controllers—such as PID or feed forward algorithms—translate velocity and position commands into precise wheel torques or joint forces. These controllers compensate for mechanical friction, load variations, and actuator dynamics, ensuring accurate movement and stability.

Path Planning Algorithms

Path planning transforms a desired goal into a collision free trajectory. Classical algorithms like A* or D* Lite explore discretized maps, while sampling based planners such as RRT* or PRM handle high dimensional spaces efficiently. Modern AMRs often employ hybrid planners that combine global planning with local replanning to adapt to unforeseen obstacles.

Obstacle Avoidance and Reactive Control

Reactive control layers operate on a much shorter time scale than path planners. Techniques such as Dynamic Window Approach (DWA), Velocity Obstacles, or Model Predictive Control (MPC) compute safe velocity commands in real time, ensuring the robot can dodge sudden obstacles while following a higher level path.

High Level Decision Making and Planning

Beyond motion, AMRs must decide on tasks, schedules, and resource allocation. Hierarchical task planners, often implemented with finite state machines or behavior trees, orchestrate sequences of subtasks—picking, transporting, charging—while maintaining overall mission objectives. Integration with warehouse management systems (WMS) or manufacturing execution systems (MES) allows AMRs to align with broader operational workflows.

Decision Making in Autonomous Mobile Robots

Decision making is where perception and control converge with artificial intelligence to produce autonomous behavior. The sophistication of these decisions determines how well a robot can handle uncertainty, adapt to changing environments, and collaborate with humans.

Machine Learning and AI Integration

Deep learning models, particularly convolutional neural networks (CNNs) and recurrent neural networks (RNNs), enable AMRs to interpret complex visual scenes, predict motion trajectories, and classify objects. Transfer learning and continual learning techniques allow robots to refine their models on the fly, reducing the need for extensive offline training.

Rule Based Systems

While AI offers flexibility, deterministic rule based systems provide transparency and predictability—critical attributes for safety critical applications. By encoding domain knowledge into logical rules, engineers can enforce hard constraints (e.g., never exceed a speed limit in a human occupied zone) and simplify verification processes.

Reinforcement Learning Approaches

Reinforcement learning (RL) treats navigation and manipulation as sequential decision making problems, where a robot learns policies that maximize cumulative rewards. RL has shown promise in tasks like warehouse picking, where the robot must learn efficient pick and place strategies. However, sample efficiency and safety remain active research areas.

Multi Agent Coordination

In many industrial scenarios, fleets of AMRs operate concurrently. Multi agent coordination frameworks—such as decentralized consensus protocols, market based task allocation, or swarm intelligence—enable robots to share information, avoid collisions, and optimize collective performance. Communication protocols like ROS (Robot Operating System) or MQTT facilitate real time data exchange.

Applications of Autonomous Mobile Robots in Automation and Control Engineering

AMRs have permeated sectors that traditionally relied on manual labor or fixed machinery. Their adaptability and intelligence make them ideal for tasks that require flexibility, precision, and continuous operation.

Manufacturing and Warehousing

- Automated Guided Vehicles (AGVs) and AMRs: Replacing fixed conveyor belts, AMRs can transport parts between workstations, reducing bottlenecks and increasing throughput.
- Inventory Management: Equipped with barcode scanners and RFID readers, AMRs maintain accurate stock counts, reducing human error.
- Collaborative Robots (Cobots): AMRs can work side by side with human operators, providing assistance in assembly lines while maintaining safety through advanced sensing.

Logistics and Delivery

- Last mile Delivery: Autonomous drones and ground robots deliver packages directly to customers, cutting down delivery times and costs.
- In warehouse Logistics: AMRs manage inbound and outbound freight, automatically sorting parcels based on destination, size, or priority.

Healthcare and Hospitals

- Medical Supply Delivery: AMRs transport medications, laboratory samples, and surgical instruments between wards and operating rooms.
- Patient Assistance: Mobile robots guide visitors, escort patients, and provide basic services like delivering water or reading schedules.
- Disinfection and Sterilization: Equipped with UV lights or chemical sprayers, AMRs perform routine sanitation tasks, reducing infection risks.

Construction and Mining

- Material Handling: Autonomous loaders, dump trucks, and drilling rigs move heavy materials without human operators in hazardous environments.
- Site Surveying: Drones and ground robots capture 3D maps of construction sites, aiding in progress monitoring and safety compliance.

Agriculture and Precision Farming

- Field Monitoring: AMRs equipped with multispectral cameras assess crop health, soil moisture, and pest infestations.

- Planting and Harvesting: Autonomous tractors and harvesters perform repetitive tasks with high precision, reducing labor costs and improving yields.

Service Robots and Domestic Applications

- Household Assistance: Vacuuming robots, lawn mowers, and personal assistants perform routine chores, freeing time for residents.
- Retail and Hospitality: Robots greet customers, guide them through stores, or serve drinks, enhancing customer experience.

Challenges and Future Trends

Baca Juga (Artikel Terkait)

- **automaker mini software version v8 erptoboss**
  URL: http://art-consciousness.com/automaker-mini-software-version-v8-erptoboss.pdf
- **automata and computability**
  URL: http://art-consciousness.com/automata-and-computability.pdf
- **automata and languages theory and applications**
  URL: http://art-consciousness.com/automata-and-languages-theory-and-applications.pdf
- **automata and mechanical toys**
  URL: http://art-consciousness.com/automata-and-mechanical-toys.pdf

Tags: #autonomous #mobile #robots #sensing #control #decision #making #applications #automation #control #engineering